



DREAM & Fractal

Vivien Quéma, Philippe Laumay
Projet Sardes, INRIA Rhône-Alpes

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Plan

- Motivations
- DREAM overview
- Feedback



Motivations

- One objective of *Sardes* is to provide administration functions for scalable distributed systems
- The primary administration task is the system observation (monitoring)
 - Requirements of scalable observation functions
- Observation ?
 - Need to reify system state changes
 - → What to monitor ? How to monitor ? ...
 - Need of an infrastructure to send and receive events
 - → ***Open technology for dynamic creation of events channel***



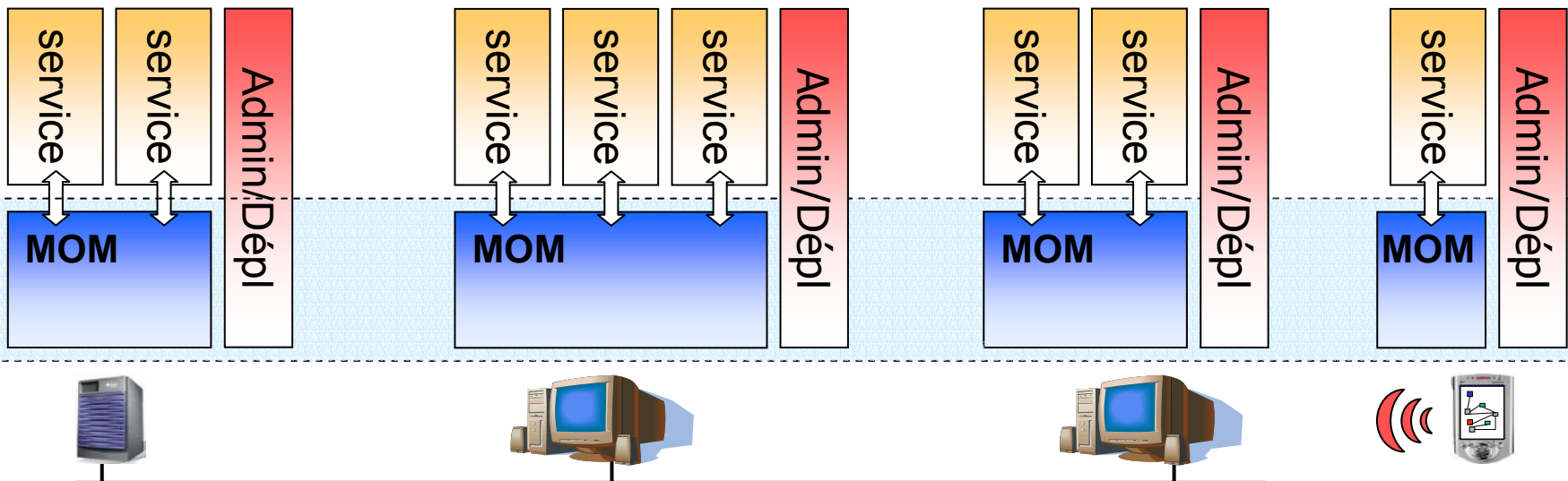
Adaptive asynchronous middleware

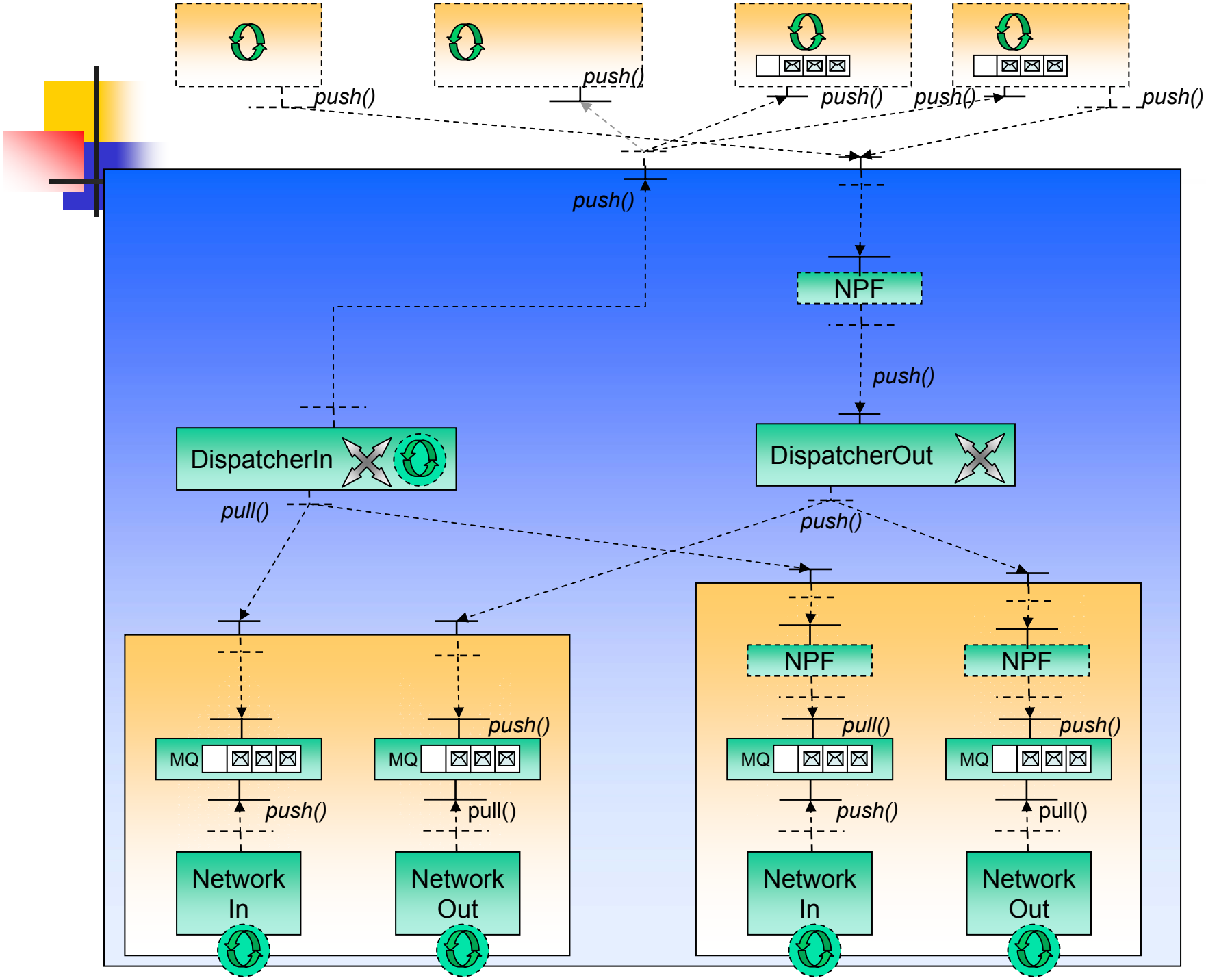
- Objectives

- Asynchronous
- Modular (component-based)
- Configurable
- Adaptive (dynamically reconfigurable)

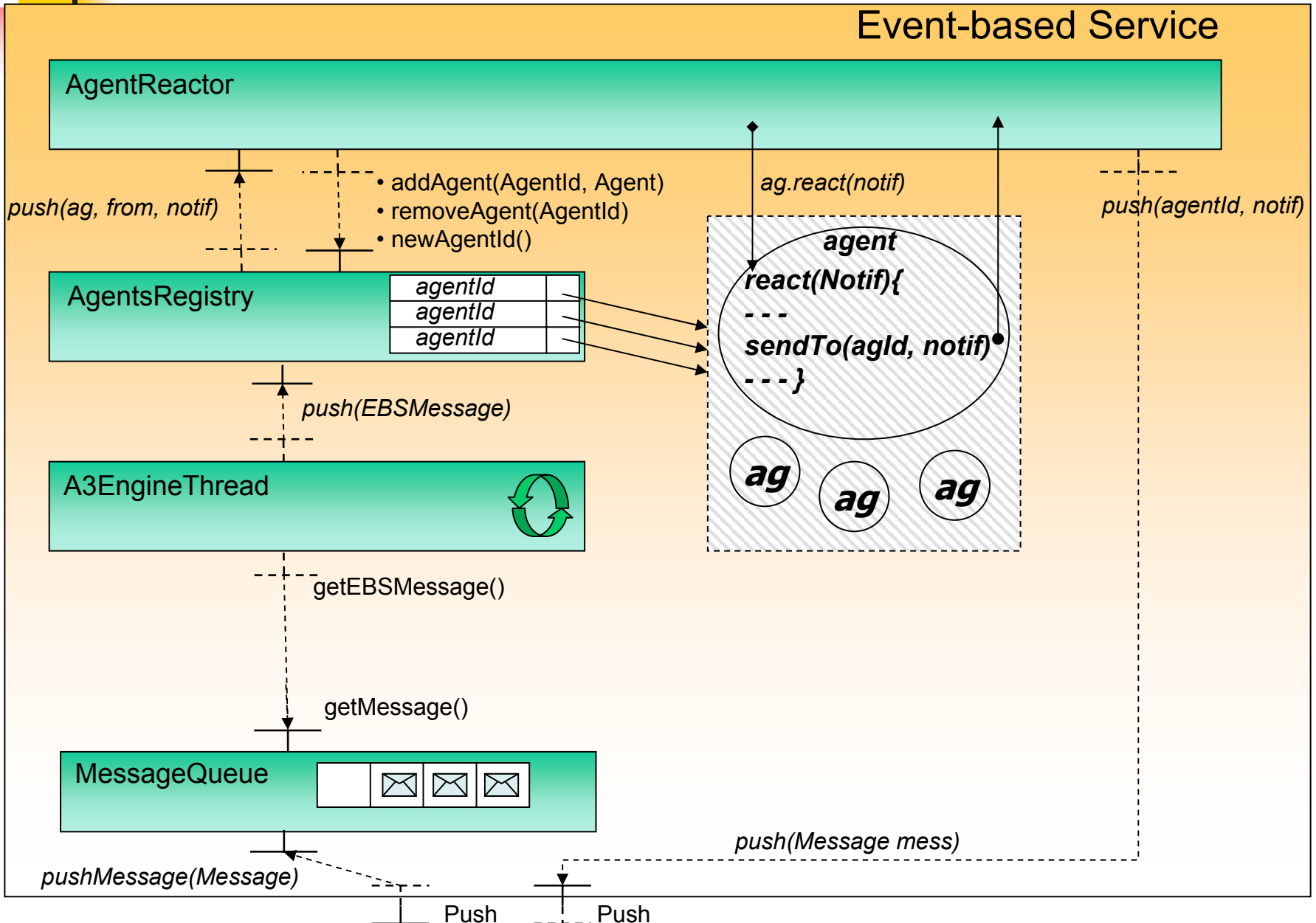
DREAM : a Dynamic REflective Asynchronous Middleware

- Message-Oriented Middleware
 - Provides message queuing facilities
- Services use the MOM
 - Produce and consume messages
 - Implement a specific functionality
- Deployment and administration tool on each site





Event-based service





Feedback (1)

- This preliminary work had two objectives
 - Componentization of the A3 middleware
 - Learn the fractal framework and evaluate the advantages of fractal over traditional object languages and over other component models



Feedback (1)

- Fractal is a minimal component model (not a framework dedicated to “business components”)
 - Adapted to the construction of middleware
 - Non functional services are not provided
 - Control interfaces are not imposed by the framework
 - It is possible to define our own controllers to implement required control operations
 - It is possible to control the overhead induced by the Julia implementation thanks to code optimization



Feedback (2)

- Fractal

- Allows to hierarchically structure the middleware
 - Primitive components for basic functions
 - Message queues
 - Sockets
 - Dispatchers
 - ...
 - Composite components
 - Composing several components to form higher-level components
 - MOM, Services
 - Network



Feedback (3)

- Fractal is recursive
 - Composite may encapsulate other composite
 - Network composites are encapsulated in the MOM composite
 - That allows a hierarchical distribution of control operations
 - Each composite only manages the components it encapsulates
 - For example, 2 network composites may have different reconfiguration capabilities



Future work

- Study dynamic aspects of the MOM reconfiguration
 - Definition of other control interfaces ?
 - Specialization of existing controllers



Conclusion

- Questions ?